

interconnection of

proportional only control may allow for more simple algorithms but it leads to weaknesses in steady state accuracy with low gain and oscillations from overshoot with high gain

the purpose of a control valve actuator is to provide the motive force to operate a valve mechanism both sliding stem and rotary control valves enjoy the same selection of actuators pneumatic

thus a cascade control system consists of two feedback control loops one nested inside the other a very common example of cascade control is a valve positioner which receives a command signal

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